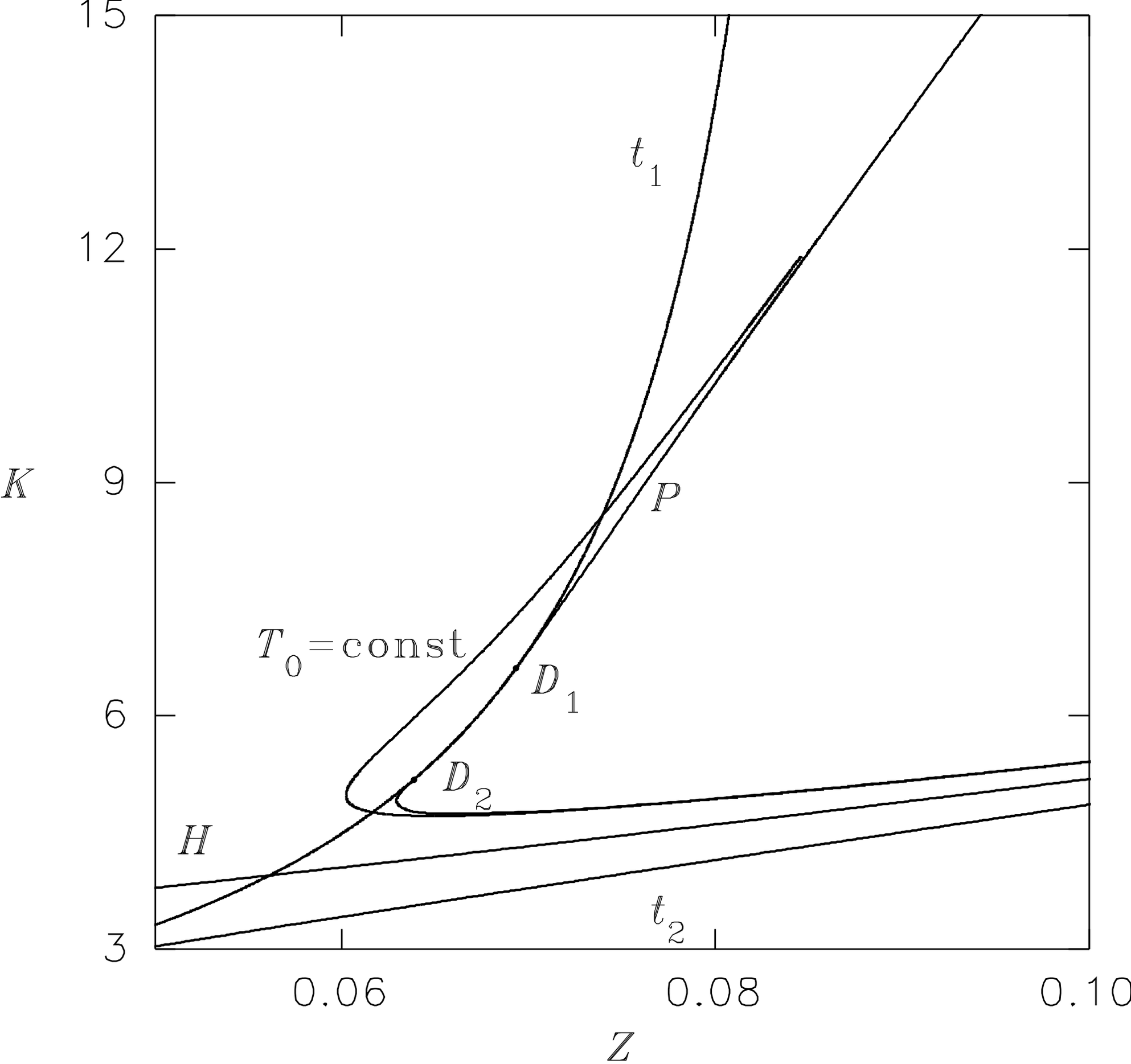
15
12
9
6
3
K
0.06
0.08
0.10
Z
t_1
t_2
P
D_1
D_2
H
$T_0 = \text{const}$